



International Conference on
**Distributed Systems: Optimization
and Economic-Environmental Applications**

(DSO'2000)

Proceedings

Editors:

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Ekaterinburg, Russia,
30 May – 2 June, 2000

PARALLEL METHODS FOR QUASILINEAR SINGULARLY PERTURBED REACTION-DIFFUSION EQUATIONS ¹

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Keywords: elliptic PDEs, boundary layer, diffusion with predominant reaction, parallel computations, ε -uniform convergence.

On the rectangle \bar{D} , where $D = \{x : 0 < x_s < d_s, s = 1, 2\}$ we consider Dirichlet's problem for the quasilinear singularly perturbed elliptic equation

$$L_{(1)}(u(x)) \equiv \varepsilon^2 \sum_{s=1,2} a_s(x) \frac{\partial^2}{\partial x_s^2} u(x) - g(x, u(x)) = 0, \quad x \in D, \quad (1a)$$

$$u(x) = \varphi(x), \quad x \in \Gamma. \quad (1b)$$

Here $\Gamma = \bar{D} \setminus D$, the functions $a_s(x)$, $g(x, u)$ and $\varphi(x)$ are sufficiently smooth, respectively, on the sets \bar{D} , $\bar{D} \times R$ and on the sides Γ_j , $\Gamma = \cup_j \Gamma_j$, $j = 1, \dots, 4$, $\varphi(x)$ is continuous on Γ . Assume $0 < a_0 \leq a_s(x) \leq a^0$, $x \in \bar{D}$,

$$(\partial/\partial u) g(x, u) \geq g_0 > 0 \quad \text{for all } (x, u) \in \bar{D} \times [-M_{(2)}, M_{(2)}], \quad (2)$$

where $M_{(2)}$ is a sufficiently large number. The perturbation parameter ε takes arbitrary values from the half-interval $(0, 1]$; say $\varepsilon \ll 1$.

Model problems of similar kind arise, for example, in numerical modelling of stationary diffusion processes accompanied by first-order chemical reactions. The parameter ε characterizes the diffusion coefficient of the involved matter, and the constant g_0 refer to the reaction rate.

As $\varepsilon \rightarrow 0$, regular boundary layers appear in small neighbourhoods of the smooth parts of the boundary Γ , and corner (elliptic) layers appear in a neighbourhood of the set Γ_0 of the corner points. The data in (1) are assumed to satisfy the necessary compatibility conditions on Γ_0 .

For problem (1) we construct an iterative domain decomposition scheme, that converges ε -uniformly and also allows for parallel computations.

Let us first give an iteration-free difference scheme. On the set \bar{D} we introduce the rectangular grid

$$\bar{D}_h = \bar{w}_1 \times \bar{w}_2, \quad (3)$$

where $\bar{w}_s = \{x_s^i : 0 = x_s^0 < \dots < x_s^{N_s} = d_s\}$ is a (possibly) nonuniform mesh

¹This work was supported in part by the Russian Foundation for Basic Research (grant 98-01-00362), and by the Netherlands Organization for Scientific Research NWO (dossier nr. 047-008-007).

on $[0, d_s]$, $s = 1, 2$. Define $h_s^i = x_s^{i+1} - x_s^i$, $x_s^i, x_s^{i+1} \in \bar{\omega}_s$; let $h \leq MN^{-1}$, where $^2 h = \max_{i,s} h_s^i$, $N = \min\{N_1, N_2\}$.

We approximate problem (1) by the finite difference scheme

$$\Lambda_{(4)}(z(x)) \equiv \varepsilon^2 \sum_{s=1,2} a_s(x) \delta_{\bar{x}\bar{x}\bar{x}} z(x) - g(x, z(x)) = 0, \quad x \in D_h, \quad (4a)$$

$$z(x) = \varphi(x), \quad x \in \Gamma_h. \quad (4b)$$

Here $D_h = D \cap \bar{D}_h$, $\Gamma_h = \Gamma \cap \bar{D}_h$, $\delta_{\bar{x}\bar{x}\bar{x}} z(x) = z_{\bar{x}\bar{x}\bar{x}}(x)$ is the second-order (central) difference derivative on the non-uniform mesh $\bar{\omega}_s$ [1].

The difference scheme (4), (3) is monotone [1]. Using majorant functions and taking into account certain *a priori* estimates (see, e.g., [2]), we find: $|u(x) - z(x)| \leq M\varepsilon^{-1}N^{-1}$, $x \in \bar{D}_h$. So this scheme converges, as $N \rightarrow \infty$, for fixed values of the parameter ε , but it does not converge ε -uniformly.

Note that we evaluate the errors in the maximum norm (in L_∞). Other norms, e.g., the L_p -norms ($1 \leq p < \infty$) and the weighted energy norm $\|\cdot\|_\varepsilon$, are unsatisfactory: in these norms the boundary layer vanishes for $\varepsilon \rightarrow 0$.

Now we introduce the special grid depending on ε

$$\bar{D}_h^* = \bar{\omega}_1^* \times \bar{\omega}_2^*. \quad (5)$$

Here $\bar{\omega}_s^* = \bar{\omega}_s^*(\sigma_s)$ is a piecewise uniform mesh refined in the neighbourhood of the end-points of $[0, d_s]$. In each interval $[0, \sigma_s]$ and $[d_s - \sigma_s, d_s]$ we use a fine mesh with step-size $h_s^{(1)} = 4\sigma_s N_s^{-1}$, and in $[\sigma_s, d_s - \sigma_s]$ we use a coarse mesh with step-size $h_s^{(2)} = 2(d_s - 2\sigma_s)N_s^{-1}$. We take $\sigma_s = \min\{4^{-1}d_s, m_1^{-1}\varepsilon \ln N_s\}$, where $0 < m_1 < m_0$, $m_0 = (g_0/a^0)^{1/2}$.

Let the solution $U_0(x)$ of the reduced equation $g(x, U_0(x)) = 0$, $x \in \bar{D}$, satisfy the estimate

$$|\partial^k U_0(x) / \partial x_1^{k_1} \partial x_2^{k_2}| \leq M_{(6)}, \quad x \in \bar{D}, \quad k \leq 2. \quad (6)$$

Theorem 1. Assume in (1) that $a_1, a_2 \in C^l(\bar{D})$, $g \in C^{l,l}(\bar{D} \times [-M_1, M_1])$, $\varphi \in C^l(\bar{D})$, and let $u \in C^l(\bar{D})$, $l = 4 + \alpha$, $\alpha > 0$, where $M_1 = M_0 M_{(6)}$, $M_0 > 18$, and also let condition (2) be true with $M_{(2)} = M_1$. Then the difference scheme (4), (5) converges, as $N \rightarrow \infty$, ε -uniformly with an error bound given by

$$|u(x) - z(x)| \leq MN^{-2} \ln^2 N, \quad x \in \bar{D}_h^*.$$

Let the connected sets

$$D^k, \quad k = 1, \dots, K \quad (7)$$

with piecewise smooth boundaries Γ^k , $\Gamma^k = \bar{D}^k \setminus D^k$, cover the domain D :

² Here and below M, M_l (m, m_l) denote sufficiently large (small) positive constants independent of ε .

$D = \bigcup_{k=1}^K D^k$. We denote by $D^{[k]}$ the union of the subdomains D^1, \dots, D^K excluding the set D^k : $D^{[k]} = \bigcup_{i=1, i \neq k}^K D^i$. We denote the minimal overlap of the sets D^k and $D^{[k]}$ by Δ^k , and also let Δ denote the least value of Δ^k , $k = 1, \dots, K$, i.e.

$$\Delta = \min_{k, x^1, x^2} \rho(x^1, x^2), \quad x^1 \in \bar{D}^k, \quad x^2 \in \bar{D}^{[k]}, \quad x^1, x^2 \notin \{D^k \cap D^{[k]}\}, \quad (8)$$

$k = 1, \dots, K$, where $\rho(x^1, x^2)$ is the distance between the points $x^1, x^2 \in \bar{D}$. In general, the value Δ may depend on the parameter ε : $\Delta = \Delta(\varepsilon)$.

Now we construct a Schwartz method modified for implementation in a parallel environment with $P \geq 1$ processors. This construction follows [3,4].

Let each subdomain D^k , $k = 1, \dots, K$ from (7) be partitioned in P disjoint non-overlapping parts (some of them may be empty): $D^k = \bigcup_{p=1}^P D_p^k$, $k = 1, \dots, K$, $\bar{D}_i^k \cap \bar{D}_j^k = \emptyset$, $i \neq j$. Assume $\Gamma_p^k = \bar{D}_p^k \setminus D_p^k$.

On the sets \bar{D}_p^k we construct the coherent meshes

$$\bar{D}_{ph}^k = \bar{D}_p^k \cap \bar{D}_h, \quad k = 1, \dots, K, \quad p = 1, \dots, P, \quad (9a)$$

where $\bar{D}_h = \bar{D}_{h(3)}$ or $\bar{D}_h = \bar{D}_{h(5)}^*$. Let $\Gamma_{ph}^k = \bar{D}_{ph}^k \setminus D_{ph}^k$.

Given the function $z^0(x)$ on \bar{D}_h satisfying condition (4b), we find the sequence of the functions $z^r(x)$, $x \in \bar{D}_h$, $r = 1, 2, \dots$ from the solutions of the discrete problems

$$\Lambda_{(4)} \left(\left. \begin{aligned} z_p^{r+\frac{k}{K}}(x) &= 0, & x \in D_{ph}^k \\ z_p^{r+\frac{k}{K}}(x) &= z^{r+\frac{k-1}{K}}(x), & x \in \Gamma_{ph}^k \end{aligned} \right\}, \quad p = 1, \dots, P; \right) \quad (9b)$$

$$z^{r+\frac{k}{K}}(x) = \begin{cases} z_p^{r+\frac{k}{K}}(x), & x \in \bar{D}_{ph}^k, \quad p = 1, \dots, P, \\ z^{r+\frac{k-1}{K}}(x), & x \in \bar{D}_h \setminus \bar{D}^k \end{cases}, \quad x \in \bar{D}_h, \quad k = 1, \dots, K, \\ z^{r+1}(x) = z^{r+\frac{K}{K}}(x), \quad x \in \bar{D}_h; \quad r = 0, 1, 2, \dots \quad (9c)$$

Under the condition

$$\Delta = \Delta_{(8)}(\varepsilon) > 0, \quad \varepsilon \in (0, 1], \quad \inf_{\varepsilon \in (0, 1]} [\varepsilon^{-1} \Delta_{(8)}(\varepsilon)] > 0, \quad (10)$$

we obtain the estimate (see [3] for the linear case)

$$|z(x) - z^r(x)| \leq Mq^r, \quad x \in \bar{D}_h, \quad (11)$$

where $q \leq 1 - m$, e. g., we can take $q = \exp(-m_0 \varepsilon^{-1} \Delta)$. If condition (10) is violated, the functions $z^r(x)$ do not converge ε -uniformly with respect to the number r of iterations. On the special grid $\bar{D}_{h(5)}^*$ we have the estimate

$$|u(x) - z^r(x)| \leq M [N^{-2} \ln^2 N + q^r], \quad x \in \bar{D}_h^*. \quad (12)$$

Emphasize that the estimate for q in (11), (12) is independent of ε .

Theorem 2. *The condition (10) is necessary and sufficient for ε -uniform convergence (as $r \rightarrow \infty$) of the functions $z^r(x)$, i. e., the solutions of the decomposition scheme (9), (3) with P parallel solvers, to the solution $z(x)$ of the base scheme (4), (3). If the hypotheses of Theorem 1 and also condition (10) are fulfilled, the solutions $z^r(x)$ of scheme (9), (5) converge, as $N, r \rightarrow \infty$, to the solution $u(x)$ of the boundary value problem (1) ε -uniformly. Under condition (10), the estimates (11), (12) are valid.*

The difference scheme is nonlinear. To solve the problem, we apply a linearization procedure [1], replacing $g(x, z^r(x))$ by $c(x)(z_{(i)}^r(x) - z_{(i-1)}^r(x)) + g(x, z_{(i-1)}^r(x))$. Here $z_{(i)}^r(x)$ is the i -th inner iteration, the function $c(x)$ satisfies the condition $c(x)u - g(x, u) \geq c_0 u$, $c_0 > 0$, where $(\partial/\partial u)g(x, u) \leq g^0$, $(x, u) \in \bar{D} \times [-M_{(2)}, M_{(2)}]$.

Thus, for parallelization of the computational method, we have constructed iterative difference schemes that converge ε -uniformly with respect to both the number N of grid nodes and the number r of (outer) iterations required for convergence of the iterative process.

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